

Dynamics and collisions of anisotropic particles settling in turbulence: application to cloud microphysics

Aurore Naso

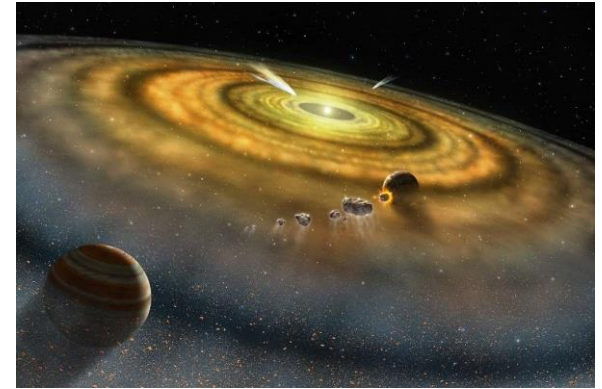
Laboratoire de **M**écanique des **F**luides et d'**A**coustique
CNRS, École Centrale de Lyon, Université de Lyon, INSA de Lyon

[Alain Pumir](#), [Jennifer Jucha](#), [Muhammad Zubair Sheikh](#),
[Facundo Cabrera](#), Mickael Bourgoïn, Nicolas Plihon

(Laboratoire de Physique, ENS Lyon)

Bernhard Mehlig, [Kristian Gustavsson](#) (Gothenburg University, Sweden)

[Emmanuel Lévêque](#) (LMFA)



Particles in turbulence (solid inclusions, drops, bubbles)



Turbulent transport of small ($d < \eta$) inclusions

Lagrangian description of particles motion by a **force balance**:

$$m_p \frac{d\mathbf{V}}{dt} = m_p \mathbf{g} + m_f \left(\frac{D\mathbf{U}}{Dt} - \mathbf{g} \right) + \mathbf{F}_P$$

\mathbf{F}_P (force due to the particle) = ???

Turbulent transport of small ($d < \eta$) inclusions

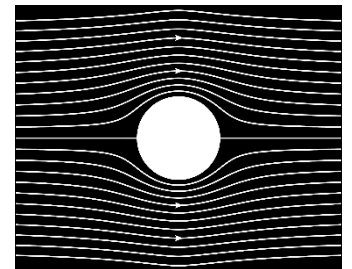
Basset-Boussinesq-Oseen equation (spherical solid particle)

Boussinesq, C. R. Acad. Sci. Paris 1885; Basset, 1888
(revisited by *Gatignol, J. Mech. Theor. Appl. 1983; Maxey & Riley, PoF 1983*)

$$m_p \frac{d\mathbf{v}_p}{dt} = m_f \frac{D\mathbf{u}}{Dt} + 6\pi r \mu_f (\mathbf{u} - \mathbf{v}_p) + \frac{1}{2} m_f \left(\frac{D\mathbf{u}}{Dt} - \frac{d\mathbf{v}_p}{dt} \right) + 6r^2 (\pi \mu_f \rho_f)^{1/2} \int_0^t \frac{d(\mathbf{u} - \mathbf{v}_p)/d\tau}{(t - \tau)^{1/2}} d\tau + (m_p - m_f) \mathbf{g}$$

= Fluid acceleration + Stokes drag + Added mass + History force + Buoyancy

Expression derived assuming a Stokes flow
at the particle scale: $Re_p = 2r|\mathbf{u}-\mathbf{v}|/\nu \ll 1$!!!



Turbulent transport of small ($d < \eta$) inclusions

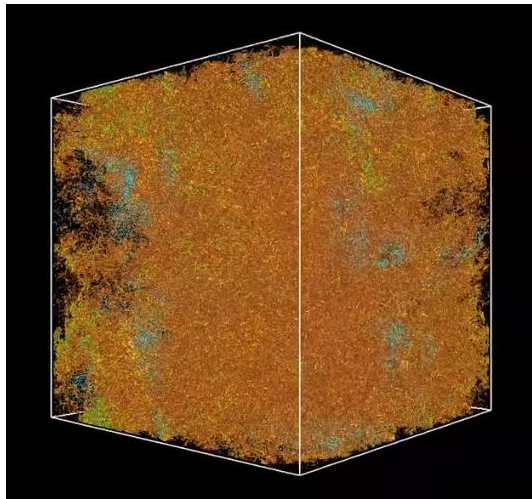
In the limit of small, **spherical**, **very dense** particles, $\rho_p/\rho_f \gg 1$

(e.g., sand in air, water droplets in air, ...)

$$m_p \frac{d\mathbf{v}_p}{dt} = 6\pi r \mu_f (\mathbf{u} - \mathbf{v}_p) + m_p \mathbf{g}$$

→

$$\frac{d\mathbf{v}'_p}{dt} = \frac{\mathbf{u}' - \mathbf{v}'_p}{St} + \mathbf{g}'$$



Ireland & Collins

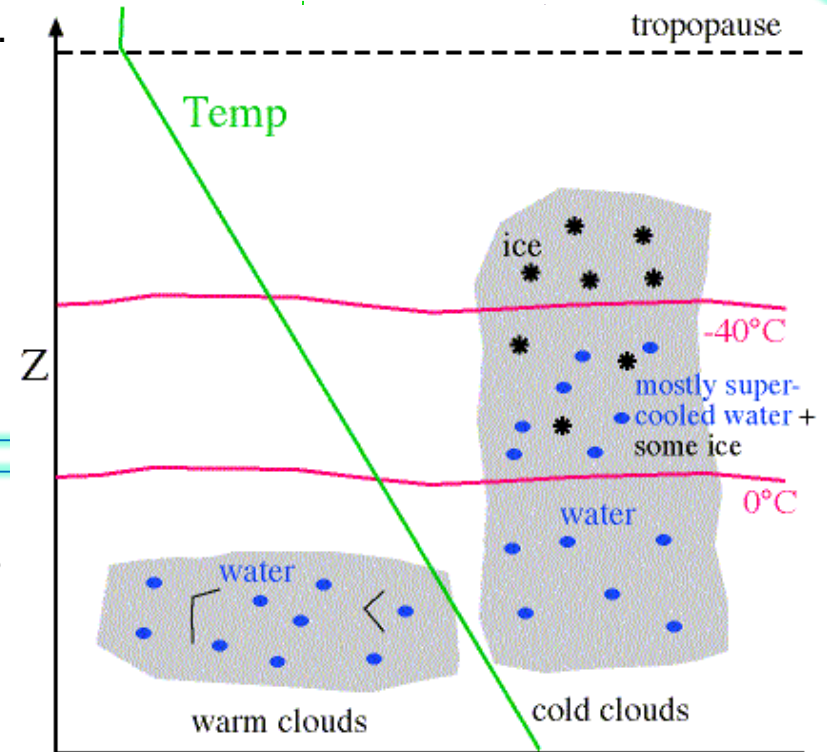
$$St = \frac{2r^2}{9\nu\tau_\eta} \frac{\rho_p}{\rho_f} = \tau_p / \tau_\eta$$

Stokes number

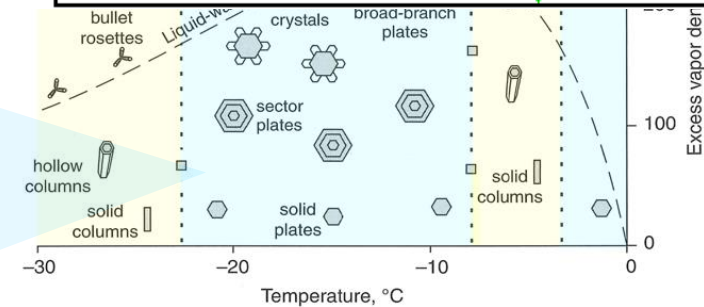
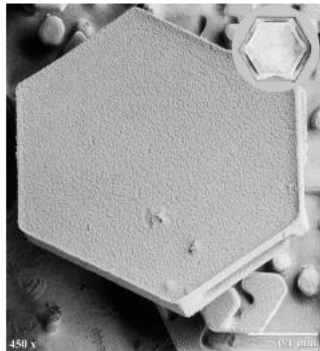
- $St \ll 1$: particle ~ fluid tracer
- $St \uparrow$: particle inertia \uparrow

Ice particles in cold clouds

- Cold clouds (top $< 0^\circ\text{C}$) contain ice particles.



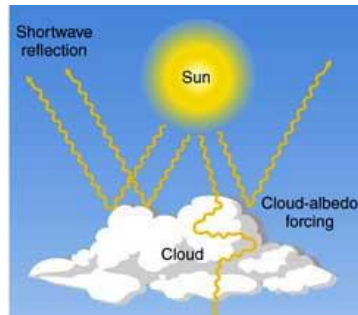
- For $-20^\circ\text{C} \lesssim T \lesssim -10^\circ\text{C}$, these particles are shaped like plates.



W. Brune (after Lamb and Verlinde)

Settling, orientation, collisions and aggregation of particles in cold clouds

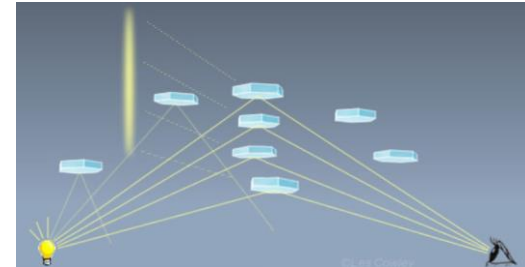
- Ice crystals **orientation**
→ EM waves (light) **reflexion**, albedo



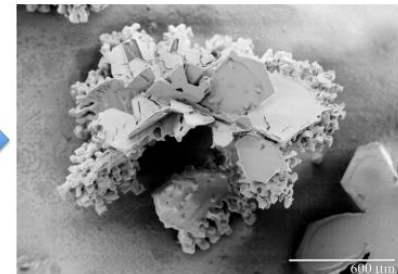
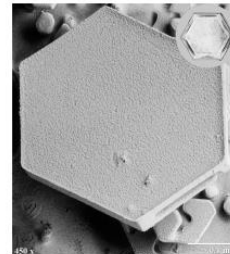
See also *Bréon & Dubrulle, JAS 2004.*



<https://www.atoptics.co.uk/halo/lpil.htm>



- **Collision** and aggregation of ice crystals
→ formation of **graupels**

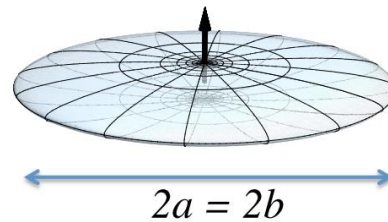
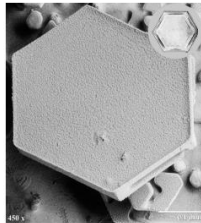


Electron and confocal microscopy laboratory,
US Agriculture Research Center

Purpose of the study

- Determination of the **crystals orientation and settling velocity**, and of their **collision rate**, in **turbulent** conditions and with **gravity**.
Direct numerical simulation of an idealized system.

- Assume that the crystal is a **thin oblate ellipsoid of revolution** (spheroid):
 $c \ll b=a$.



$$\beta \equiv a/c$$

- Small ($a < \eta$), heavy ($\rho_p \gg \rho_f$) and spheroidal particle.
- Equation of motion ? **Force and torque** acting on the spheroid ?

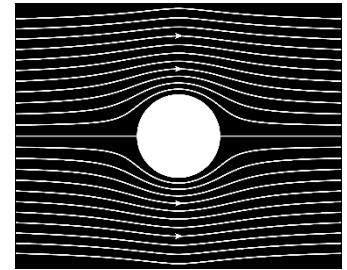
**Equations of motion of the spheroids:
the role of fluid inertia**

Equations of motion of the spheroids

- Translational and rotational dynamics of spheroidal particles in turbulence:
For particles \neq fluid tracers, need to write equations of motion

$$m_p \frac{d\mathbf{v}}{dt} = \text{hydrodynamic force} + \text{buoyancy}$$
$$I_p \frac{d\boldsymbol{\omega}}{dt} = \text{hydrodynamic torque}$$

- Using Stokes approximation: hydrodynamic force = Stokes force
hydrodynamic torque = Jeffery's torque



For a spherical object: $\mathbf{F}_{Stokes} = 6\pi r \mu_f (\mathbf{u} - \mathbf{v}_p)$

First effect of fluid inertia:

$$\mathbf{F}_{Oseen} = \mathbf{F}_{Stokes} \times \left(1 + \frac{3Re_p}{16} \right) \sim \mathbf{F}_{Stokes} \text{ if } Re_p \ll 1 \quad (\text{in practice if } r \ll \eta)$$

Translational motion (Stokes)

$$\frac{d\mathbf{r}_C}{dt} = \mathbf{v}_C,$$
$$\frac{d\mathbf{v}_C}{dt} = \frac{v\rho_f}{m_C} \mathbf{R}^{-1} \hat{\mathbf{K}} \mathbf{R} \cdot [\mathbf{u}(\mathbf{r}_C, t) - \mathbf{v}_C] + \mathbf{g}$$

- $\hat{\mathbf{K}}$: anisotropic resistance tensor, expressed in the eigenframe of the particle
- \mathbf{R} : rotation matrix (laboratory frame \rightarrow particle eigenframe)
- \mathbf{u} : fluid velocity
 \mathbf{v}_C : particle velocity

Rotational motion (Stokes)

- **Angular momentum:** (Jeffery, 1922)

$$\frac{d}{dt} \begin{pmatrix} \Omega_x \\ \Omega_y \\ \Omega_z \end{pmatrix} = \begin{pmatrix} \Omega_y \Omega_z \frac{\beta^2 - 1}{1 + \beta^2} \\ \Omega_z \Omega_x \frac{1 - \beta^2}{1 + \beta^2} \\ 0 \end{pmatrix} + 20 \frac{\rho_f}{\rho_p} \frac{v}{a^2} \begin{pmatrix} \frac{1}{\alpha_0 + \beta^2 \gamma_0} & 0 & 0 \\ 0 & \frac{1}{\alpha_0 + \beta^2 \gamma_0} & 0 \\ 0 & 0 & \frac{1}{2\alpha_0} \end{pmatrix} \begin{pmatrix} \frac{1 - \beta^2}{1 + \beta^2} \hat{S}_{yz} + (\hat{\Omega}_{zy} - \Omega_x) \\ \frac{\beta^2 - 1}{1 + \beta^2} \hat{S}_{xz} + (\hat{\Omega}_{xz} - \Omega_y) \\ (\hat{\Omega}_{yx} - \Omega_z) \end{pmatrix}$$

Ω : angular velocity of the particle (in its reference frame !)

$$A_{ij} = \partial_j u_i$$

$$\hat{\mathbf{A}} = \mathbf{R} \mathbf{A} \mathbf{R}^{-1},$$

$$\hat{\mathbf{S}} = \frac{1}{2} (\hat{\mathbf{A}} + \hat{\mathbf{A}}^t),$$

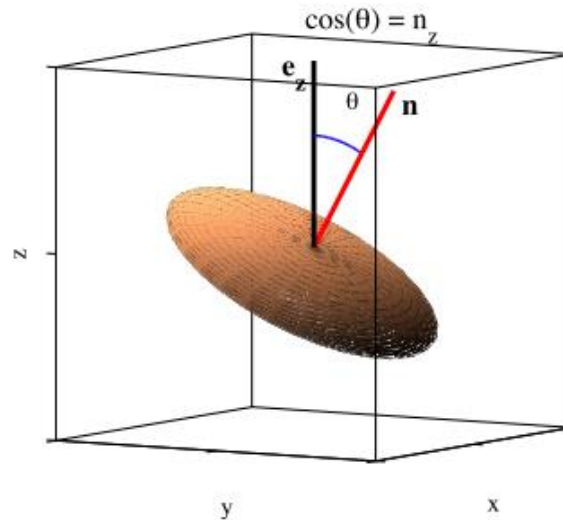
$$\hat{\mathbf{\Omega}} = \frac{1}{2} (\hat{\mathbf{A}} - \hat{\mathbf{A}}^t)$$

- **Orientation of the spheroid:**

$$d\mathbf{R}/dt = \mathbf{\Omega} \cdot \mathbf{R}$$

Orientation statistics

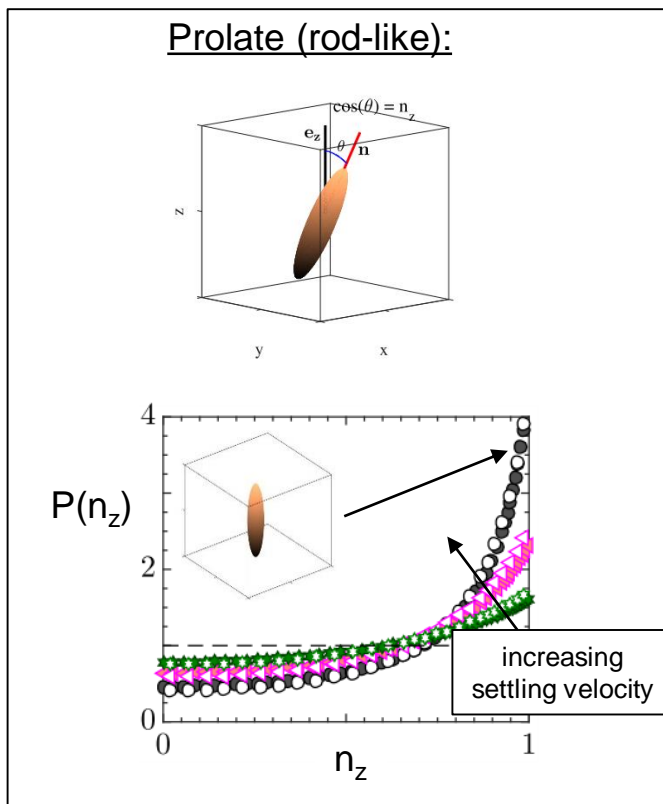
- \mathbf{n} = normal vector to the axisymmetry plane of the crystal;
- $\mathbf{g} = -g \mathbf{e}_z$ (\mathbf{e}_z points upwards).



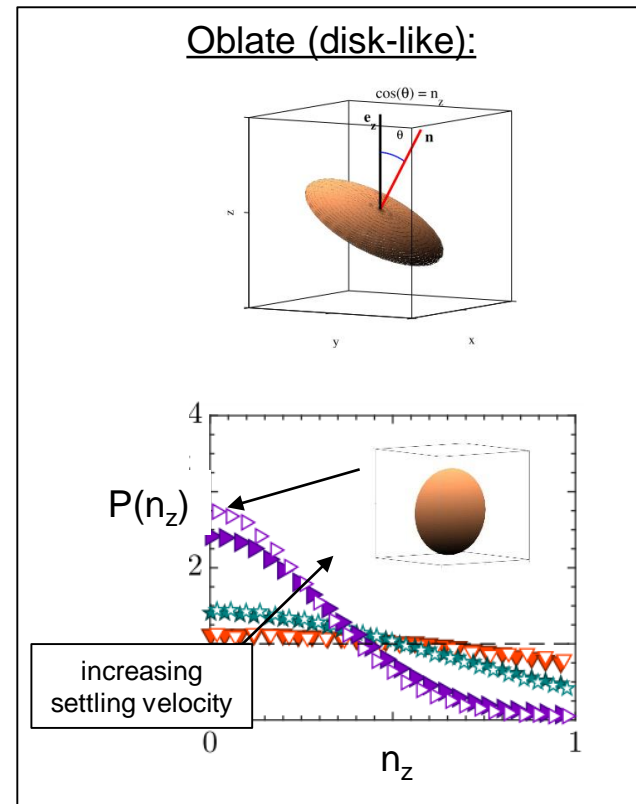
Settling of spheroids in a turbulent flow: orientation distribution calculated numerically using Stokes torque

- Integration of the resulting set of equations for particles suspended in a turbulent flow (*Gustavsson et al, 2014; Siewert et al, 2014a,b; Gustavsson et al, 2017; Jucha et al, 2018; Naso et al, 2018*):

If W_s (settling velocity) $>$ U_0 (fluid velocity), the orientation distribution is biased (“vertical”):

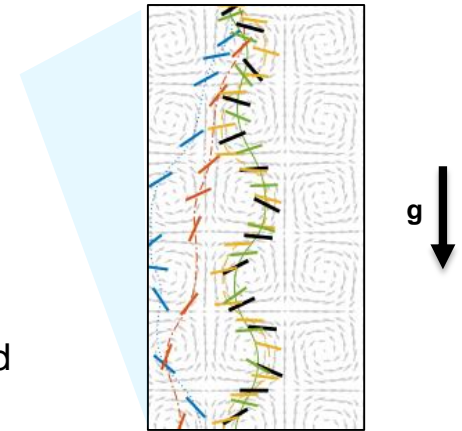


g



First effect of fluid inertia on the rotational motion of settling spheroids

- Experimental results:
 - * *Lopez & Guazzelli, PRF 2017*: rods in a 2D laminar flow
→ “horizontal” settling
 - * *Kramel, PhD 2017*: rods in turbulence
→ “horizontal” settling
 - * *Roy et al, JFM 2019; Cabrera et al, 2021*: rods in quiescent fluid
→ “horizontal” settling



Results opposite to those obtained by DNS in turbulent flows using Stokes approximation !

- Fluid inertia correction on rotational motion of spheroids recently derived for arbitrary aspect ratios (*Dabade et al, JFM 2015*).

Problem: fluid-inertia torque ~ Stokes torque !!!

This inertial correction → “horizontal” settling.

- Determine the conditions under which fluid inertia can be neglected for the angular dynamics of spheroids settling in turbulence.

Angular motion of spheroids

$$\text{Hydrodynamic torque: } \hat{\mathbf{T}} = \hat{\mathbf{T}}_{St} + \hat{\mathbf{T}}_I$$

“Stokes” contribution
(*Jeffery, 1922*)

Contribution due to fluid inertia
for a particle moving steadily
in a homogeneous flow
(*Dabade et al, 2015*)

- NB: Fluid inertia can also induce corrections due to shear (*Candelier, Mehlig & Magnaudet, JFM 2019*) and unsteadiness.

- Estimate the ratio $|\hat{\mathbf{T}}_I|/|\hat{\mathbf{T}}_{St}|$:

* $|\hat{\mathbf{T}}_I|/|\hat{\mathbf{T}}_{St}| \ll 1$: Stokes expected to dominate (“vertical” settling if $W_s > U_0$)

* $|\hat{\mathbf{T}}_I|/|\hat{\mathbf{T}}_{St}| \gg 1$: inertia expected to dominate (“horizontal” settling if $W_s > U_0$)

Evaluation of the ratio $|\mathbf{T}_{St}|/|\mathbf{T}_I|$

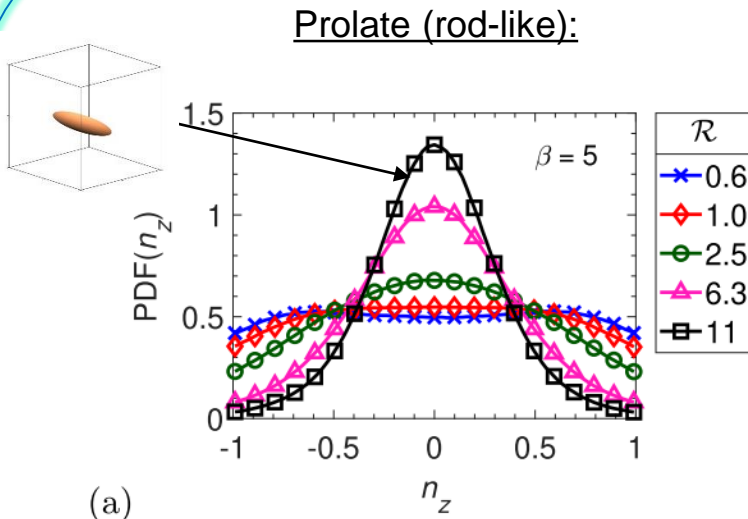
- For very flat disks (aspect ratio $\beta \ll 1$) and for thin rods ($5 \leq \beta \leq 100$), it can be shown that:

$$|\hat{\mathbf{T}}_I|/|\hat{\mathbf{T}}_{St}| \sim \mathcal{R} \equiv \left(\frac{W_s}{U_0}\right)^2 Re_f^{1/2}$$

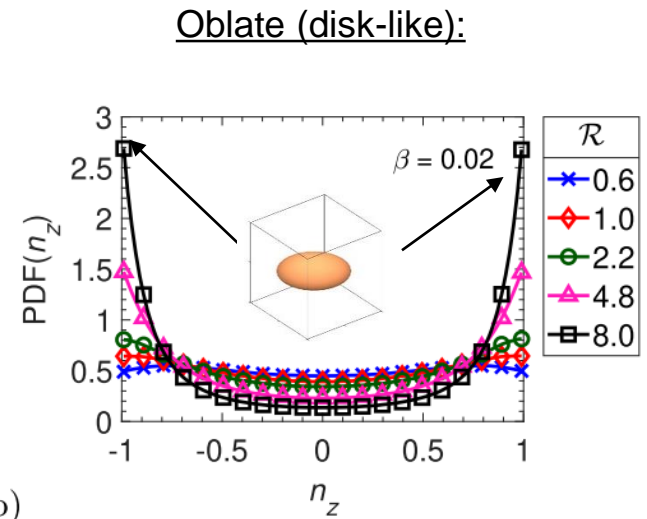
$Re_f = U_0 L / \nu$: large scale Reynolds number of the flow

- Therefore, in the high Re_f regime, the fluid-inertia torque can be neglected (i.e., \mathcal{R} can be small) only if W_s/U_0 is small
→ orientation distribution nearly uniform
- The Stokes contribution can be neglected ($\mathcal{R} \gg 1$) simultaneously with a large ratio W_s/U_0
→ biased “horizontal” distribution
- **Therefore the orientation bias obtained in numerical works which neglect the fluid-inertia torque (biased “vertical” distribution) cannot be observed at large Re_f !!!**

Numerical results in homogeneous and isotropic turbulence



(a)



(b)

- Transition from a uniform to a biased “horizontal” distribution observed at increasing \mathcal{R} .
- Biased “vertical” distribution never observed.
- Analysis seems to be valid for any β .

Settling and collisions of ice crystals

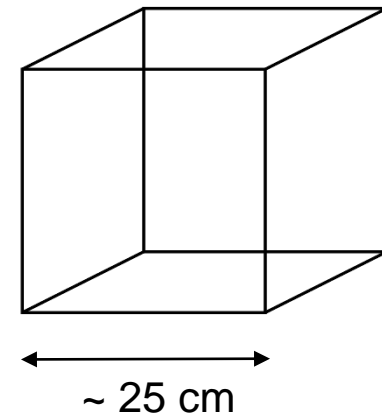
Settling, orientation and collisions of ice crystals: numerical setup

- Generation of an idealized stationary, homogeneous and isotropic turbulent flow in a cubic box with periodic boundary conditions (pseudo-spectral method).

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{\nabla p}{\rho_f} + \nu \nabla^2 \mathbf{u} + \mathbf{f},$$
$$\nabla \cdot \mathbf{u} = 0,$$

- 3 values of R_λ (or ε) considered:

Flow	I	II	III
ε (cm^2/s^3)	0.976	15.62	246.4
Re_λ	55.8	94.6	151.2
τ_K (s)	0.341	0.085	0.021
T_L (s)	1.96	0.70	0.26
u_{rms} (cm/s)	2.18	5.72	14.4
N	384	768	1576



Physical parameters

- Simulations designed for representing at best **realistic situations in cloud conditions**. Physical parameters at $T = -20^\circ\text{C}$ (*Pruppacher & Klett, 1997*).
- Parameters common to all runs:

Fluid			Ice crystals	Gravity	
ρ_f (g cm ⁻³)	ν (cm ² s ⁻¹)	μ (g cm ⁻¹ s ⁻¹)	ρ_i (g cm ⁻³)	a (μm)	g (cm s ⁻²)
1.413×10^{-3}	0.1132	1.599×10^{-4}	0.9194	150	981

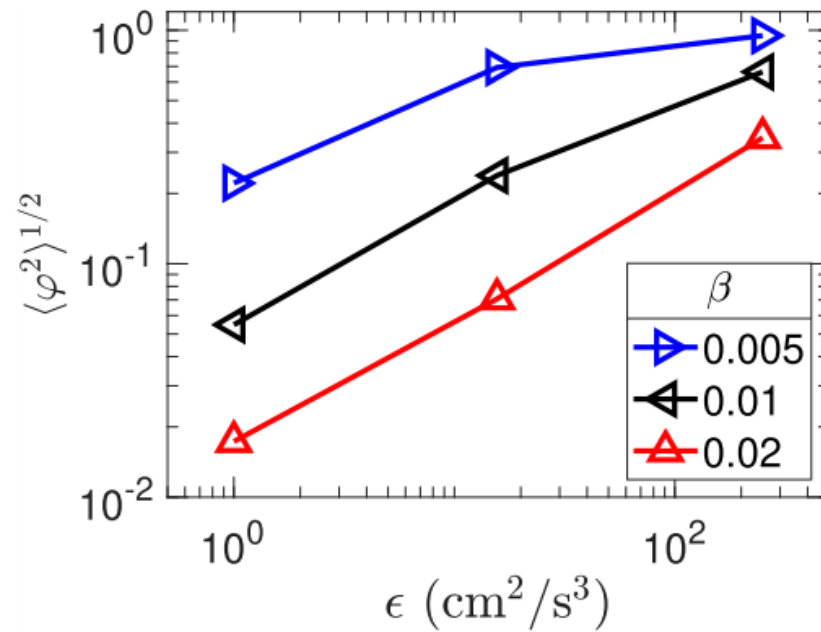
TABLE 1. Values of the physical parameters common to all runs. The fluid is moist air, whose volumetric mass, kinematic and dynamic viscosities are ρ_f , ν and μ , respectively. The density of the water droplets is ρ_l . The ellipsoidal ice crystals have a volumetric mass ρ_i and a semi-major axis a . The gravitational acceleration is denoted g .

Physical parameters

Runs	Flows	β	N_c	T_{run} (s)	$\langle U_s \rangle$ (cm/s)	St	Sv
1	I	0.005	100^3	98	1.84	$8.4 \cdot 10^{-3}$	4.89
2	I	0.01	100^3	112	3.08	$1.7 \cdot 10^{-2}$	9.78
3	I	0.02	70^3	126	5.48	$3.4 \cdot 10^{-2}$	19.6
4	II	0.005	100^3	24	2.12	$3.4 \cdot 10^{-2}$	2.44
5	II	0.01	70^3	30	3.50	$6.8 \cdot 10^{-2}$	4.89
6	II	0.02	70^3	36	5.78	0.135	9.78
7	II	0.05	70^3	31.5	11.5	0.338	24.5
8	III	0.005	100^3	5.28	2.4	0.134	1.23
9	III	0.01	100^3	5.28	4.5	0.268	2.45
10	III	0.02	100^3	5.28	7.4	0.536	4.91

w or w/o gravity.

Crystal settling: orientation statistics

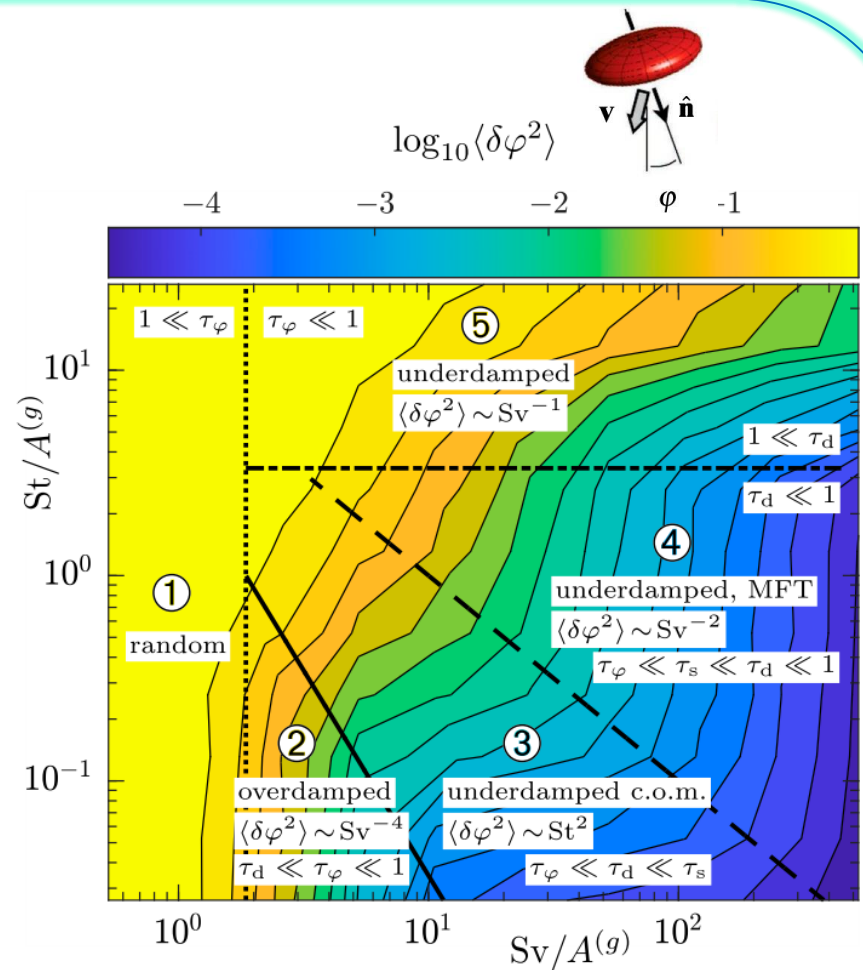


Broader orientation distribution at high ϵ (turbulence) and small β (particle inertia).

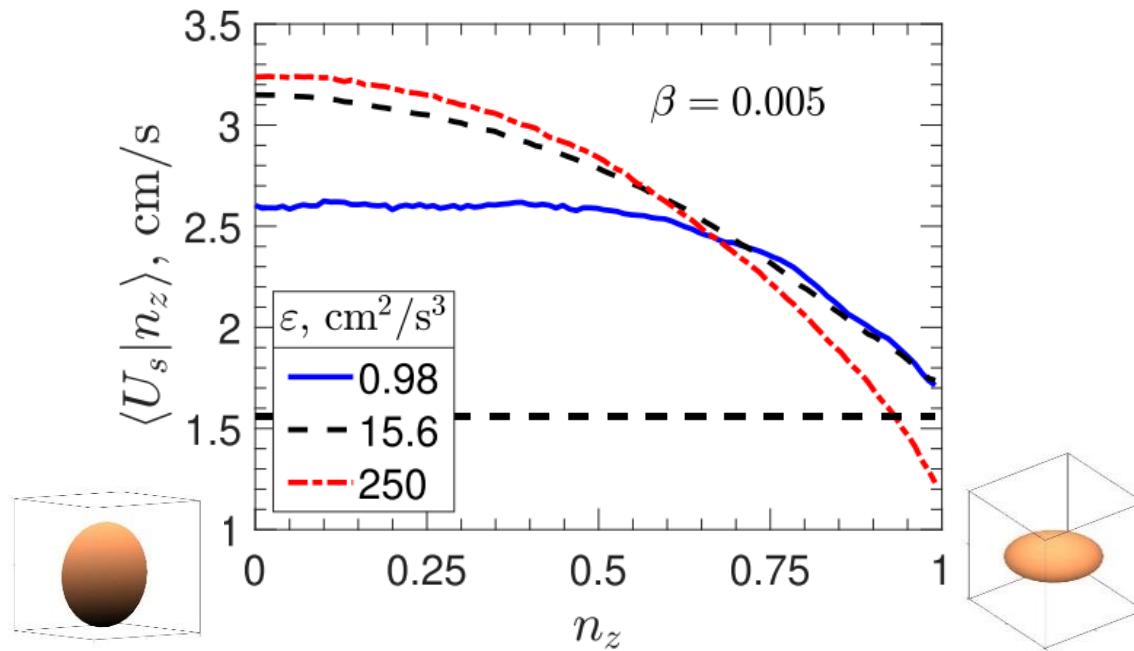
Parameter space for the orientation distribution

Theoretical modeling and numerical statistical model for orientation statistics as a function of β , $St = \tau_p / \tau_\eta$ (Stokes number) and $Sv = g\tau_p / u_\eta$ (settling number).

Gustavsson, Sheikh, Naso, Pumir & Mehlig, *J. Atm. Sci.* 2021



Settling velocity conditioned on orientation



Two particles very close to each other may have a significant velocity difference, provided that they have different orientations \rightarrow consequences for the collision rate...

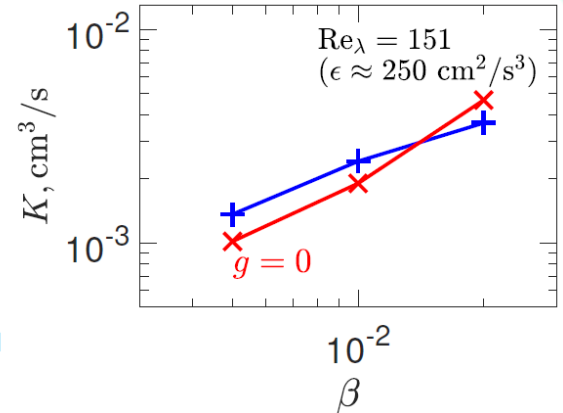
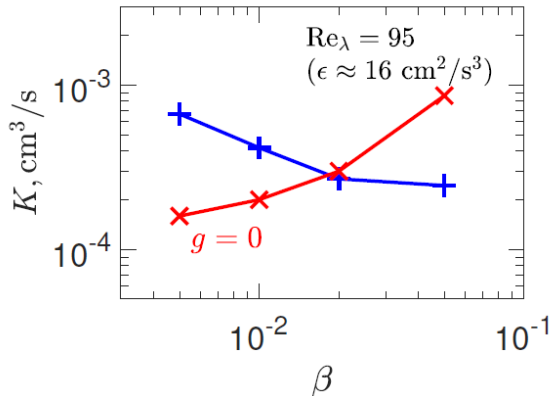
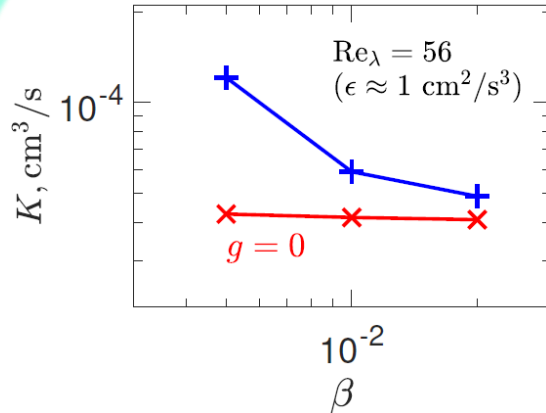
Collision kernel

$$N_c = \frac{1}{2} K \times \frac{N^2}{V} \times T$$

N_c : number of collisions.
 K : collision kernel.
 N : number of particles.

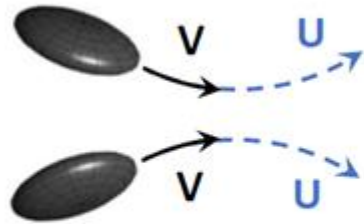
V : volume of the domain.
 T : simulation time.

Pumir & Wilkinson, ARCMP 2016



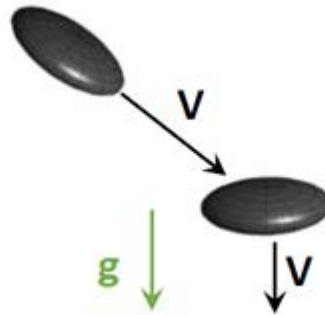
- Without gravity, K increases with β and ϵ (particle inertia), \sim spheres.
- Behavior less trivial in the presence of gravity.

Collision mechanisms for settling anisotropic particles



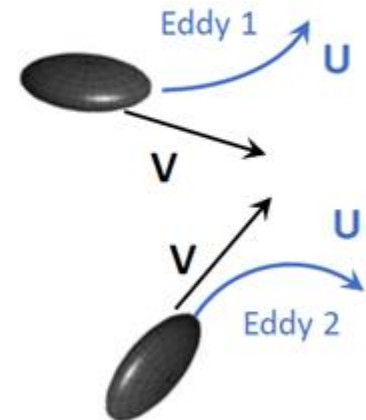
Turbulence: tracer particles brought together by velocity gradients.

Saffman & Turner, JFM 1956



Differential settling: faster spheroids fall on slower ones.

Jucha et al, PRF 2018

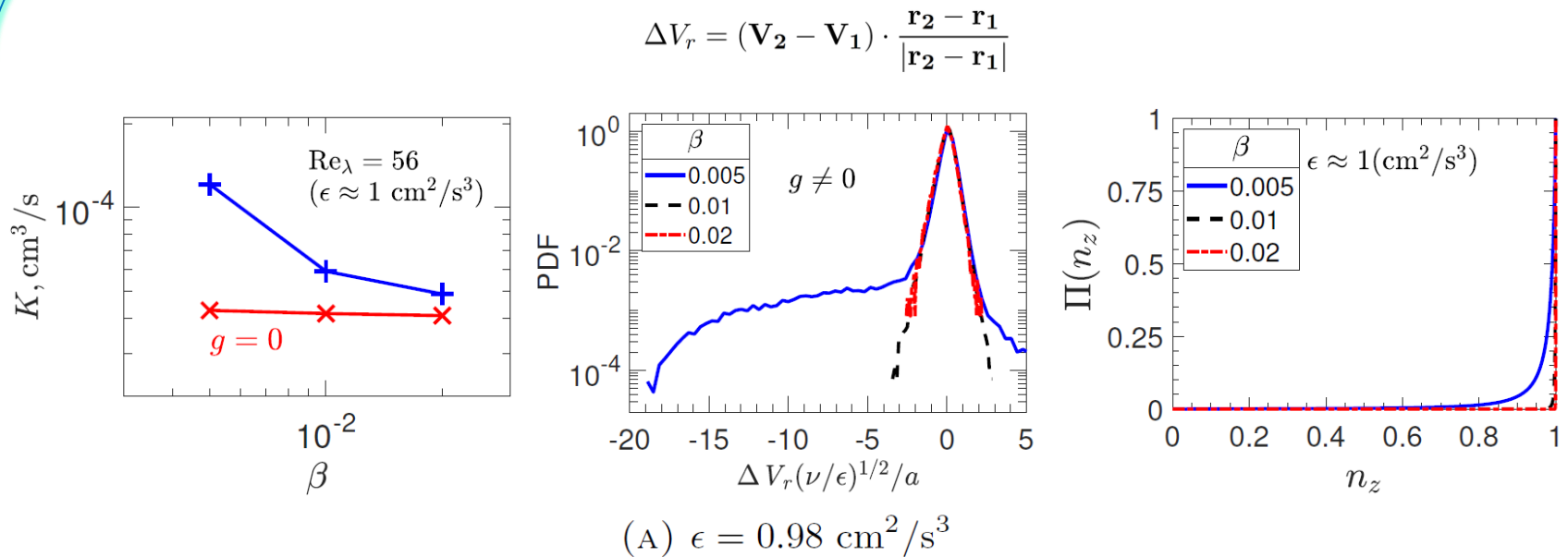


Particle inertia: particles from different locations collide due to the « sling effect ».

Falkovich & Pumir, JAS 2007

Collision kernel

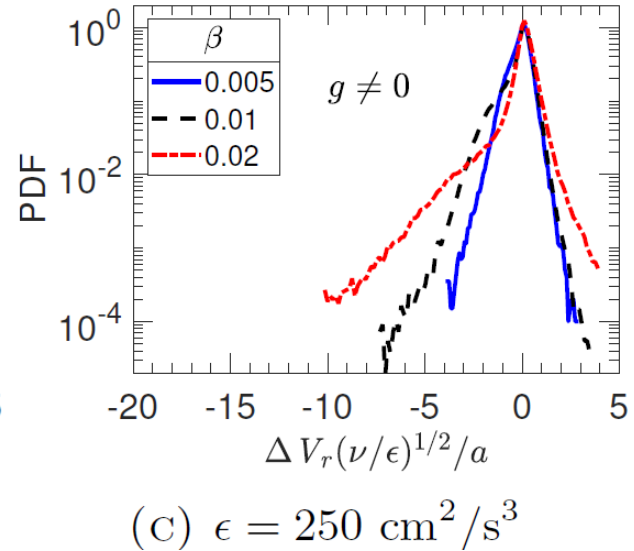
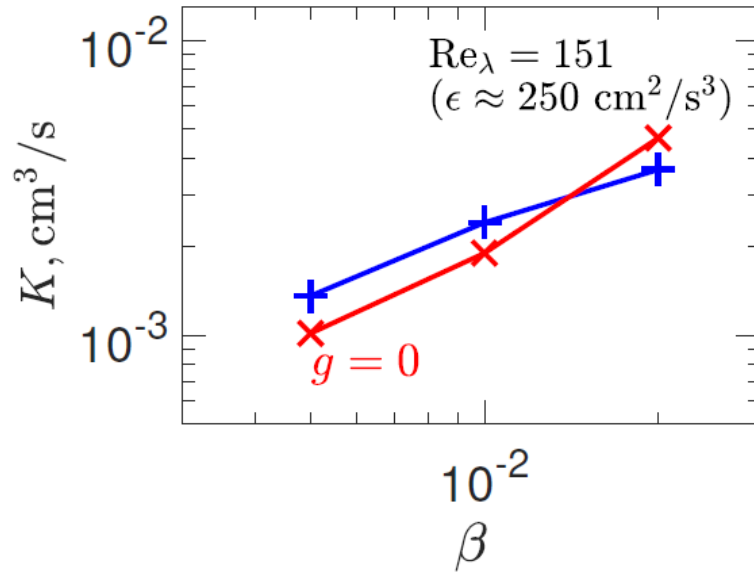
$$\epsilon = 1 \text{ cm}^2/\text{s}^3; \text{Re}_\lambda = 56 \text{ (St} < 0.04)$$



- Saffman-Turner ($K \sim 3 \cdot 10^{-5} \text{ cm}^3/\text{s}$; $\Delta v_r \sim a / \tau_\eta$) for $\beta \geq 0.01$.
- When $g \neq 0$, differential settling for $\beta = 0.005$.

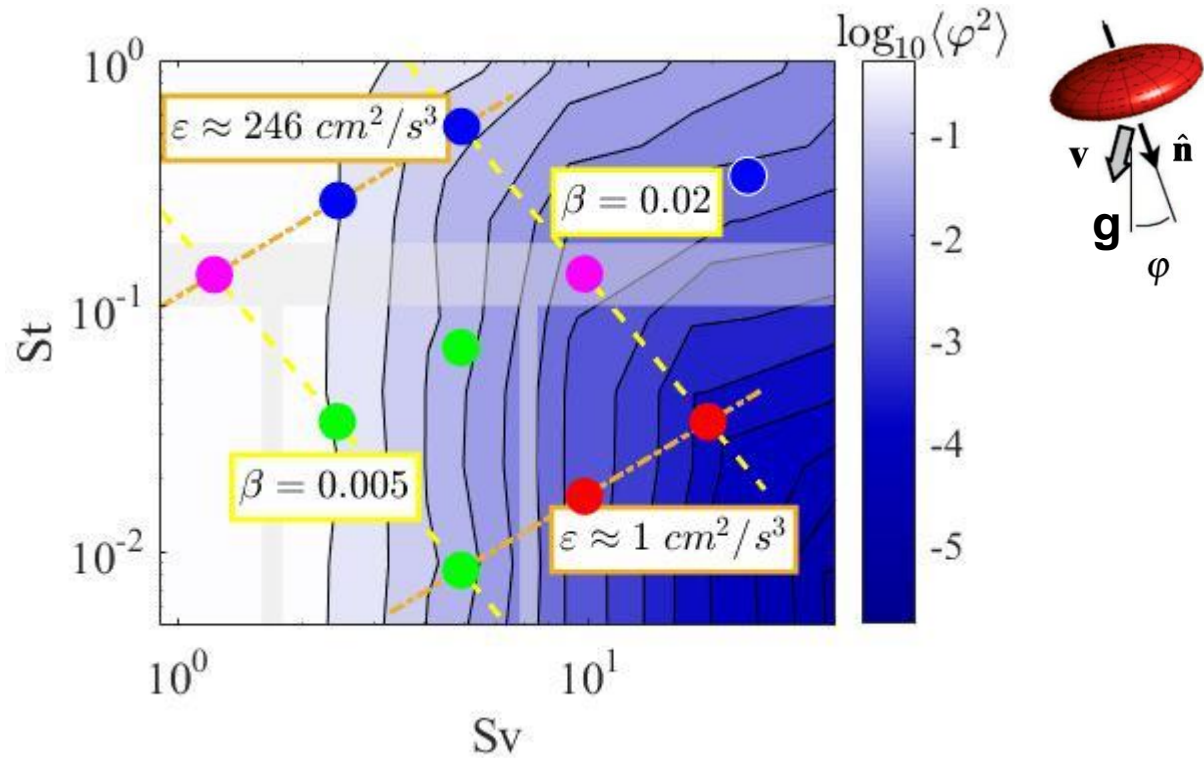
Collision kernel

$$\varepsilon = 246 \text{ cm}^2/\text{s}^3; \text{Re}_\lambda = 150 \text{ (St} = 0.1\text{-}0.6\text{)}$$



- Saffman-Turner ($\Delta v_r \sim a / \tau_\eta$) for $\beta = 0.005$.
- Inertial effects ($\text{St} \sim 0.6$) for $\beta \geq 0.01$.

Collision regimes in the (Sv, St) plane



$$St = \tau_p / \tau_\eta \text{ (Stokes number)}$$
$$Sv = g\tau_p / u_\eta \text{ (settling number)}$$

Red: Saffman-Turner
Green: differential settling
Blue: inertial effects

Summary - Discussion

Take-home message (rotational motion of settling spheroids):

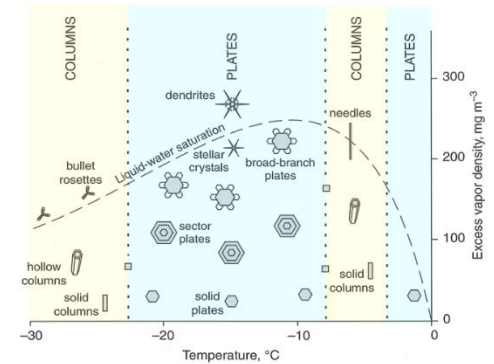
- In a turbulent flow, heavy spheroids can only settle either with a random orientation or preferentially horizontally. Neglecting the fluid-inertia torque may lead to wrong results !
- In laminar flows (not shown here), the three orientation regimes can be observed (uniform distribution, “vertical”, “horizontal”). The limit $Re_f \rightarrow 0$ requires some care.
- Our estimates were derived for very flat disks (aspect ratio $\beta \ll 1$) and for thin rods ($5 \leq \beta \leq 100$), but our numerical results show that they are also relevant for moderate values of β .

Take-home message (orientation, settling and collisions of ice crystals in clouds):

- Our results improve the predictions of orientation fluctuations of earlier works (*Cho et al, J. Atmos. Soc. 1981; Klett, J. Atmos. Sci. 1995*), and are consistent with real observations.
- The settling velocity of ice-crystals strongly depends on their orientation.
- The resulting differential settling can play a crucial role in the collisions process. Collisions driven by three mechanisms: fluid velocity gradients, differential settling, effects of particle inertia.

Limitations of the present approach:

- “One-way coupling”.
- “Ghost collision” approximation.
- Simplified crystal geometry, homogeneous mass density.
- Equations of motion valid for small Re_p .
Effects of shear and unsteadiness neglected.



W. Brune (after Lamb and Verlinde)

Perspectives:

- **Prolate** spheroids ($-10\text{ °C} \lesssim T \lesssim -5\text{ °C}$).
- Investigating further the **collision mechanisms** when particle inertia is dominant.
- Collisions between **ice crystals and supercooled water droplets** coexisting in mixed phase clouds.

